

Load balancing in dynamic networks by bounded delays asynchronous diffusion

Jacques M. Bahi ¹, Sylvain Contassot-Vivier ², Arnaud Giersch ¹

¹ - LIFC, Univ. of Franche-Comté, France

² - ALGorille Team, Loria, Univ. Henri Poincaré, Nancy, France

Contents

- * Context and objectives
- * Model
 - * Notations
 - * Assumptions
- * Choice of load ratios
- * Theoretical result
- * Experimental evaluation
 - * Context
 - * Results
- * Conclusion

Context and objectives

- * Evolution of parallel systems
 - * More and more complex:
 - * Hierarchy and heterogeneity
 - * Dynamicity: intermittent links
- ⇒ Strong demand for generic adaptive algorithms
 - ⇒ Mutation from static/centralized LB algorithms to dynamic/decentralized ones
- * The most suited are based on local exchanges but are either synchronous or assume a static net
 - ⇒ **Asynchronous Load Balancing!!**

Model

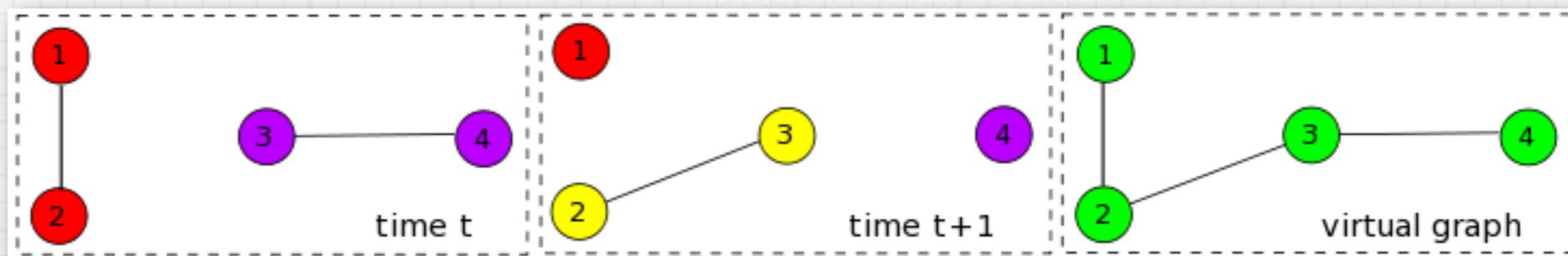
Notations

n	number of processors
$P=\{1,\dots,n\}$	set of processors
$N_i(t)$	set of processors directly connected to i at time t
$x_i(t)$	load of processor i at time t
$x_j^i(t)$	evaluation on processor i at time t of the load of processor j
$s_{ij}(t)=\alpha_{ij}(t)(x_i(t)-x_j^i(t))$	amount of load sent by i to j at time t $0 \leq \alpha_{ij}(t) \leq 1, \sum_{j=1}^n \alpha_{ij}(t) = 1,$ $\alpha_{ij}(t) = 0$ if $j \notin N_i(t)$ or $x_i(t) \leq x_j^i(t)$

Model

* Assumptions:

- * Initial condition: $\sum_{i=1}^n x_i(0) = L$
- * Communication interruptions and delays are bounded
- * Jointly connected condition



- * Continuous representation of the loads
- * When two nodes are connected, the most loaded sends a part of its load to the other
- * Remaining load on the sender will not become smaller than those on the receivers

Load ratios

- * Must ensure that the load on every node will converge towards L/n
- * Let's consider $j^* = \min_{k \in N_i(t)} x_k^i(t)$
- * We obtain the following constraints:

$$\sum_{k \in N_i(t) \setminus \{j^*\}} \alpha_{ik}(t) (x_i(t) - x_k^i(t)) \leq \beta (x_i(t) - x_{j^*}^i(t))$$

where $0 \leq \beta < 1$ is a real constant

and

$$\alpha_{ij^*}(t) = \frac{1}{2} \left(\frac{1 - \sum_{k \neq j^*} \alpha_{ik}(t) (x_i(t) - x_k^i(t))}{x_i(t) - x_{j^*}^i(t)} \right) \geq \frac{1 - \beta}{2}$$

and

$$0 \leq \alpha_{ij}(t) \leq \frac{1}{2} \left(\frac{1 - \sum_{k \neq i} \alpha_{ik}(t) (x_i(t) - x_k^i(t))}{x_i(t) - x_j^i(t)} \right)$$

Theoretical result

Theorem

Under the previous assumptions, the asynchronous load balancing algorithm below converges to $x^* = 1/n \sum_{i=1}^n x_i(0)$

Algorithm

At each time step, each processor:

1. Compares its load to the loads of its connected neighbors
2. Determines the $\alpha_{ij}(t)$ and deduces the $s_{ij}(t)$
3. Sends those loads to the corresponding neighbors
4. Receives some load from its more loaded neighbors

Experimental evaluation

- * **Context:**

- * Implementation in the SimGrid simulator

- * SimGrid:

- * Framework for testing algorithms in clusters/grids

- * Realistic computation and communication models

- * Reproducible and representative results

- * Asynchronous iterative algorithm:

- * Tasks are the elements of a domain discretization

- * Set of identical tasks with different numbers of iterations

- * Tasks can be migrated by our LB algorithm

- ⇒ one task can perform its iterations on different nodes

Local load distribution strategy

- * Our theorem gives constraints on the load amounts to send to the neighbors but no precise values
 - ⇒ Several local load distribution strategies are possible
- * **The tested one:**
 - * $\alpha_{ij}(t) = 1/(|N_i(t)| + 1) \quad \forall j \in N_i(t) \text{ s.t. } x_i(t) > x_j^i(t)$
 - * Backpack-like load distribution to compute the $s_{ij}(t)$:
 - * Not every less loaded neighbor actually receives load
 - * Tests from the least to the most loaded neighbor
 - * While the remaining local load stays larger than the load of the current neighbor plus its sent load ($s_{ij}(t)$)

Evaluation criteria

- * **Efficiency evaluation**: two percentages
 - * Overhead of our LB scheme according to a near optimal scheduling
 - * Computation of the theoretical minimal makespan without taking into account the potential tasks migrations
 - * Theoretical value, not always reachable
 - * 10% means our LB is 10% slower than the optimal
 - * Gain in execution time with our LB scheme relatively to the non-balanced version
 - * 10% means our LB saves 10% of initial execution time

Experimental contexts

Cluster	
Size	10 and 50 machines
Powers	identical or different (ratio 10)
Links	homogeneous
Initial distribution of tasks	
or	All on a single node
	Evenly distributed over the processors
Communications	
or	Always active
	Intermittent
Tasks	
Number	10000
Data size	80 bytes per task
Iterations	random in [100, 500]
Flops	1600 per iteration

Linear topology

* Most difficult case due to the longer diffusion time

Size	Initial tasks distribution	Homogeneous procs		Heterogeneous procs		Measures
		10	50	10	50	
Constant links	All tasks on one node	31.38 86.86	387.82 90.24	34.96 92.09	367.50 83.90	% overhead % gain
	Even distribution	0.44 0.97	2.33 3.13	16.25 80.64	46.26 75.31	% overhead % gain
Intermittent links	All tasks on one node	55.58 84.44	967.35 78.65	146.73 85.54	832.17 67.89	% overhead % gain
	Even distribution	0.48 0.93	3.18 2.33	52.78 74.56	99.89 66.26	% overhead % gain

Ring topology

* Better suited context due to the smaller diameter

Size	Initial tasks distribution	Homogeneous procs		Heterogeneous procs		Measures
		10	50	10	50	
Constant links	All tasks on one node	11.55 88.85	292.48 92.15	23.43 92.76	370.14 83.80	% overhead % gain
	Even distribution	0.26 1.15	2.08 3.37	2.78 82.89	44.39 75.63	% overhead % gain
Intermittent links	All tasks on one node	23.75 87.63	1187.76 74.24	127.99 86.64	1116.72 58.09	% overhead % gain
	Even distribution	0.54 0.87	3.45 2.07	34.94 77.53	80.62 69.51	% overhead % gain

Complete graph topology

- * Most favorable context due to the smallest diameter
- * Fair results due to the load distribution strategy

Size	Initial tasks distribution	Homogeneous procs		Heterogeneous procs		Measures
		10	50	10	50	
Constant links	All tasks on one node	6.12 89.39	811.01 81.78	15.24 93.25	791.51 69.29	% overhead % gain
	Even distribution	0.4 1.01	7.45 -1.72	2.8 82.89	108.62 64.79	% overhead % gain
Intermittent links	All tasks on one node	28.11 87.19	4101.52 15.97	46.96 91.39	1085.86 59.15	% overhead % gain
	Even distribution	0.31 1.09	6.74 -1.04	7.93 82.03	331.93 27.09	% overhead % gain

Complete graph topology

- * Most favorable context due to the smallest diameter
- * Fair results due to the load distribution strategy

Size	Initial tasks distribution	Homogeneous procs		Heterogeneous procs		Measures
		10	50	10	50	
Constant links	All tasks on one node	6.12 89.39	811.01 81.78	15.24 93.25	791.51 69.29	% overhead % gain
	Even distribution	0.4 1.01	4.67 0.92	2.8 82.89	108.62 64.79	% overhead % gain
Intermittent links	All tasks on one node	28.11 87.19	4101.52 15.97	46.96 91.39	1085.86 59.15	% overhead % gain
	Even distribution	0.31 1.09	3.31 2.21	7.93 82.03	331.93 27.09	% overhead % gain

- * A slightly different strategy avoids the losses (in red)

Conclusion

- * A decentralized LB scheme for use in dynamic networks has been presented
- * It is generic and can be used in conjunction with many computing algorithms
- * Its convergence has been proved for constant global load
 - * But it should also be good for occasional load variations
- * Experimental results confirm the interest of the method
 - * No sensible overhead in already balanced cases
 - * Good gains in the other cases
- * Optimal choice of the local distribution strategy must be further investigated

A study of the (auto-)tuning of the inner parameters (β and α_{ij}) and the implementation for use with a real application are the next steps!!